MC14490

Hex Contact Bounce Eliminator

The MC14490 is constructed with complementary MOS enhancement mode devices, and is used for the elimination of extraneous level changes that result when interfacing with mechanical contacts. The digital contact bounce eliminator circuit takes an input signal from a bouncing contact and generates a clean digital signal four clock periods after the input has stabilized. The bounce eliminator circuit will remove bounce on both the “make” and the “break” of a contact closure. The clock for operation of the MC14490 is derived from an internal R C oscillator which requires only an external capacitor to adjust for the desired operating frequency (bounce delay). The clock may also be driven from an external clock source or the oscillator of another MC14490 (see Figure 5).

NOTE: Immediately after powerup, the outputs of the MC14490 are in indeterminate states.

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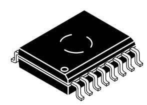
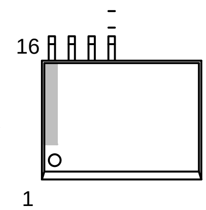


SOIC–16
DW SUFFIX
CASE 751G



Features

- Diode Protection on All Inputs
- Six Debouncers Per Package
- Internal Pullups on All Data Inputs
- Can Be Used as a Digital Integrator, System Synchronizer, or Delay Line
- Internal Oscillator (R C), or External Clock Source
- TTL Compatible Data Inputs/Outputs
- Single Line Input, Debounces Both “Make” and “Break” Contacts
- Does Not Require “Form C” (Single Pole Double Throw) Input Signal
- Cascadable for Longer Time Delays
- Schmitt Trigger on Clock Input (Pin 7)
- Supply Voltage Range = 3.0 V to 18 V
- Chip Complexity: 546 FETs or 136.5 Equivalent Gates
- These Devices are Pb Free and are RoHS Compliant
- NLV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC Q100 Qualified and PPAP Capable

MAXIMUM RATINGS (Voltages Referenced to V_{SS})

Parameter	Symbol	Value	Unit
DC Supply Voltage Range	V_{DD}	−0.5 to +18.0	V
Input or Output Voltage Range (DC or Transient)	V_{in}, V_{out}	−0.5 to V_{DD} + 0.5	V
Input Current (DC or Transient) per Pin	I_{in}	±10	mA
Power Dissipation, per Package (Note 1)	P_D	500	mW
Ambient Temperature Range	T_A	−55 to +125	°C
Storage Temperature Range	T_{stg}	−65 to +150	°C
Lead Temperature (8−Second Soldering)	T_L	260	°C

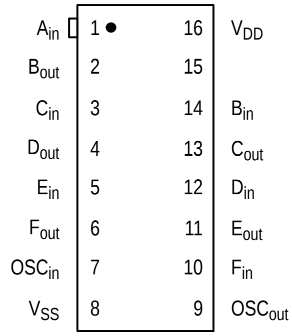
Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

1. Temperature Derating: Plastic “P and D/DW” Packages: – 7.0 mW/°C From 65°C To 125°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high−impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range $V_{SS} \leq (V_{in}$ or $V_{out}) \leq V_{DD}$.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either V_{SS} or V_{DD}). Unused outputs must be left open.

PIN ASSIGNMENT



ELECTRICAL CHARACTERISTICS (Voltages Referenced to V_{SS})

Characteristic	Symbol	V_{DD} Vdc	– 55°C Min	– 55°C Max	25°C Min	25°C Typ (Note 2)	25°C Max	125°C Min	125°C Max	Unit
Output Voltage "0" Level V_{in} = V_{DD} or 0	V_{OL}	5.0 10 15	– – –	0.05 0.05 0.05	– – –	0 0 0	0.05 0.05 0.05	– – –	0.05 0.05 0.05	Vdc
"1" Level V_{in} = 0 or V_{DD}	V_{OH}	5.0 10 15	4.95 9.95 14.95	– – –	4.95 9.95 14.95	5.0 10 15	– – –	4.95 9.95 14.95		

SWITCHING CHARACTERISTICS (Note 3) (C_L = 50 pF, T_A = 25°C)

Characteristic		Symbol	V_{DD} Vdc	Min	Typ (Note 4)	Max	Unit
Output Rise Time All Outputs		t_{TLH}	5.0 10 15	– – –	180 90 65	360 180 130	ns
Output Fall Time	Oscillator Output	t_{THL}	5.0 10 15	– – –	100 50 40	200 100 80	ns
	Debounce Outputs	t_{THL}	5.0 10 15	– – –	60 30 20	120 60 40	

THEORY OF OPERATION

The MC14490 Hex Contact Bounce Eliminator is basically a digital integrator. The circuit can integrate both up and down. This enables the circuit to eliminate bounce on both the leading and trailing edges of the signal, shown in the timing diagram of Figure 3.

Each of the six Bounce Eliminators is composed of a 4 1/2 bit register (the integrator) and logic to compare the input with the contents of the shift register, as shown in Figure 4. The shift register requires a series of timing pulses in order to shift the input signal into each shift register location. These timing pulses (the clock signal) are represented in the upper waveform of Figure 3. Each of the six Bounce Eliminator circuits has an internal resistor as shown in Figure 4. A pullup resistor was incorporated rather than a pulldown resistor in order to implement switched ground input signals, such as those coming from relay contacts and push buttons. By switching ground, rather than a power supply lead, system faults (such as shorts to ground on the signal input leads) will not cause excessive currents in the wiring and contacts. Signal lead shorts to ground are much more probable than shorts to a power supply lead.

When the relay contact is closed, (see Figure 4) the low level is inverted, and the shift register is loaded with a high on each positive edge of the clock signal. To understand the operation, we assume all bits of the shift register are loaded with lows and the output is at a high level.

At clock edge 1 (Figure 3) the input has gone low and a high has been loaded into the first bit or storage location of the shift register. Just after the positive edge of clock 1, the input signal has bounced back to a high. This causes the shift register to be reset to lows in all four bits — thus starting the timing sequence over again.

During clock edges 3 to 6 the input signal has stayed low. Thus, a high has been shifted into all four shift register bits and, as shown, the output goes low during the positive edge of clock pulse 6.

It should be noted that there is a 3 1/2 to 4 1/2 clock period delay between the clean input signal and output signal. In this example there is a delay of 3.8 clock periods from the beginning of the clean input signal.

After some time period of N clock periods, the contact is opened and at N+1 a low is loaded into the first bit. Just after N+1, when the input bounces low, all bits are set to a high. At N+2 nothing happens because the input and output are low and all bits of the shift register are high. At time N+3 and thereafter the input signal is a high, clean signal. At the positive edge of N+6 the output goes high as a result of four lows being shifted into the shift register.

Assuming the input signal is long enough to be clocked through the Bounce Eliminator, the output signal will be no longer or shorter than the clean input signal plus or minus one clock period.

The amount of time distortion between the input and output signals is a function of the difference in bounce characteristics on the edges of the input signal and the clock frequency. Since most relay contacts have more bounce when making as compared to breaking, the overall delay, counting bounce period, will be greater on the leading edge of the input signal than on the trailing edge. Thus, the output signal will be shorter than the input signal — if the leading edge bounce is included in the overall timing calculation.

The only requirement on the clock frequency in order to obtain a bounce free output signal is that four clock periods do not occur while the input signal is in a false state. Referring to

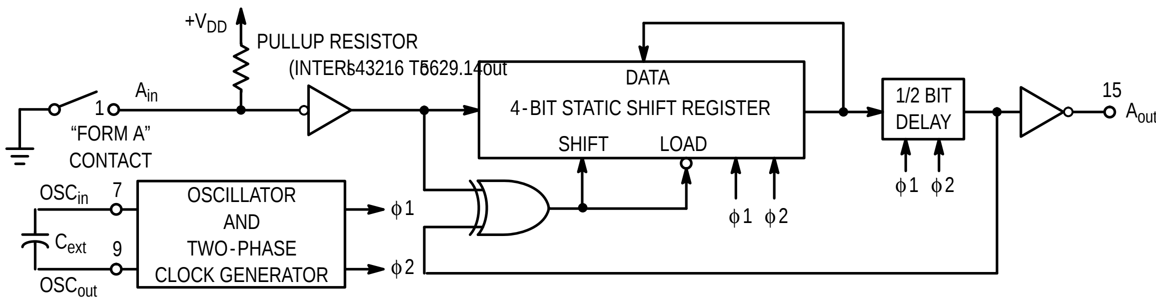


Figure 4. Typical "Form A" Contact Debounce Circuit (Only One Debouncer Shown)

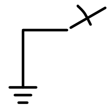


Figure 9. Single Pulse Output Circuit

ORDERING INFORMATION

Device	Package	Shipping†
MC14490DWG	SOIC−16 (Pb−Free)	47 Units / Rail
NLV14490DWG*		
MC14490DWR2G	SOIC−16 (Pb−Free)	1000 / Tape & Reel
NLV14490DWR2G*		
MC14490FG	SOEIAJ−16 (Pb−Free)	50 Units / Rail
MC14490FELG	SOEIAJ−16 (Pb−Free)	2000 Units / Tape & Reel
MC14490PG	PDIP−16 (Pb−Free)	500 Units / Rail