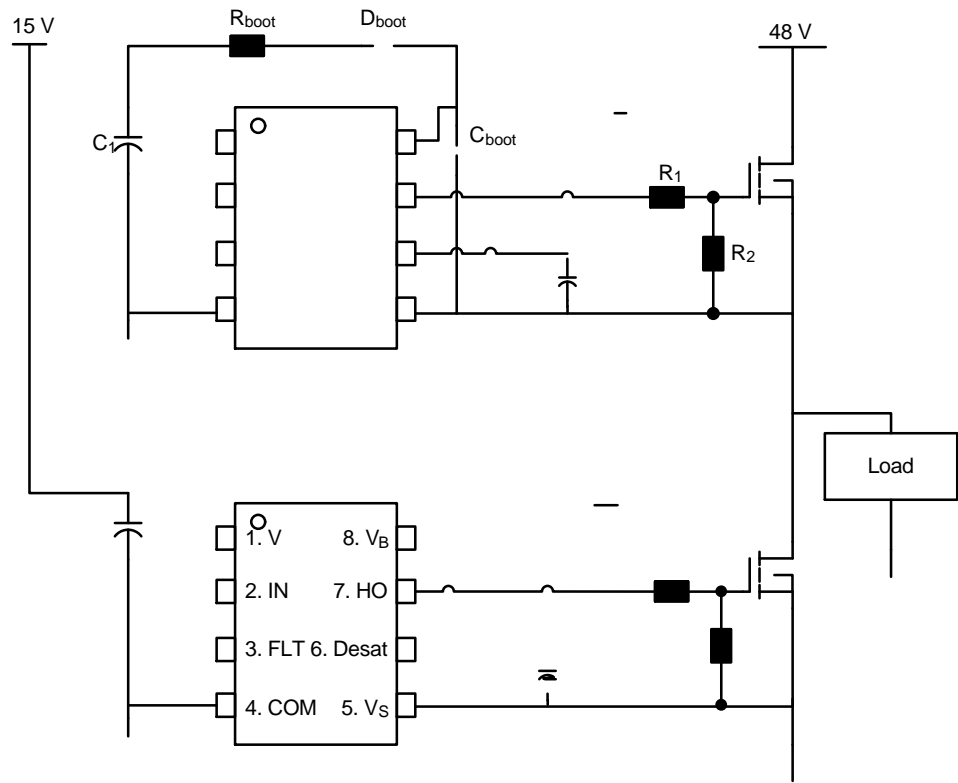




# AND90251/D



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## PIN FUNCTION DESCRIPTION

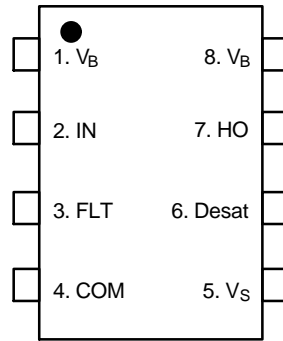


Figure 4. Pin Connection (Top View)

### PIN DESCRIPTION

Pin No.	Symbol	Description
1	$V_{DD}$	Power supply for logic stage
2	IN	Input command
3	FLT	Bi-directional Fault pin
4	COM	Ground for logic stage
5	$V_S$	Floating source connection
6	Desat	Drain to Source Desaturation detection pin
7	HO	Output
8	$V_B$	Floating Power Supply for power stage

APPLICATION EXAMPLES

**Gate Driver for 48 V DC–DC Converter Battery Switch**

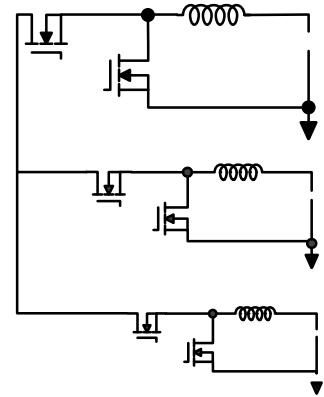
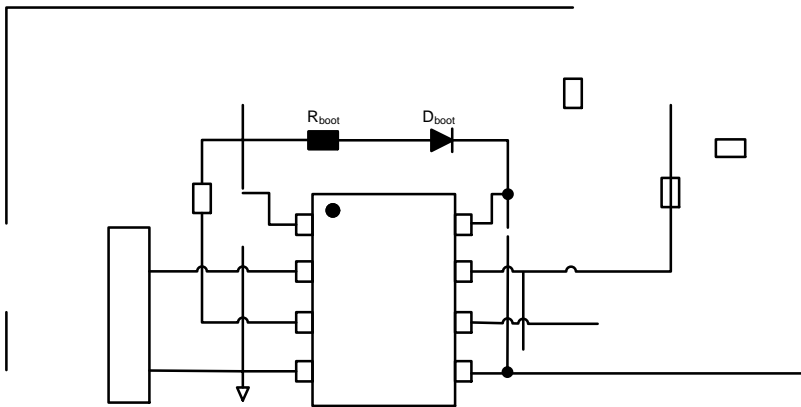
The simplified block diagram in Figure 5 shows how the FAD3171 can be used to drive a MOSFET as a battery main switch in a 48 V DC–DC converter.

The initial turn–on of the MOSFET is done through the bootstrap capacitance, initially charged by the 15 V supply. The integrated charge pump in the FAD3171 does not have enough source current capability to assure a direct energy efficient turn on of a larger die size MOSFET.

Once the MOSFET is turned on with 100% duty cycle, the bootstrap capacitance cannot charge any more through the 15 V supply and gets depleted by the continuous current sink into the gate to source resistance  $R_2$  and by the internal leakage current of the gate driver.

The charge pump integrated in the FAD3171 turns on as soon as the bootstrap voltage drops below the charge pump turn on threshold, typ. 10.8 V. The charge pump operates and supplies current until the bootstrap voltage reaches the upper charge pump turn off threshold voltage (typ. 11.2 V) or, in case current consumption is too high, the bootstrap voltage drops to the driver turn off level of typ. 7.5 V.

Note that to minimize the leakage current in the gate path, the resistance  $R_2$  should not be too low. Considering the 200  $\mu\text{A}$  current sourced by the charge pump at 9 V, excluding the desat current, the resistance  $R_2$  should be greater than 47 k $\Omega$  to maintain 9 V on the gate of the MOSFET.





**Example of a Fault Control Logic**

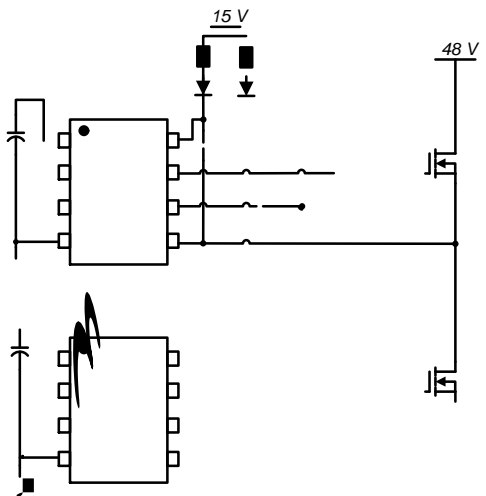
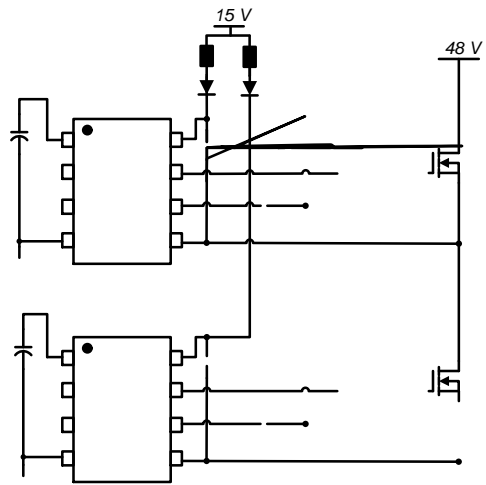
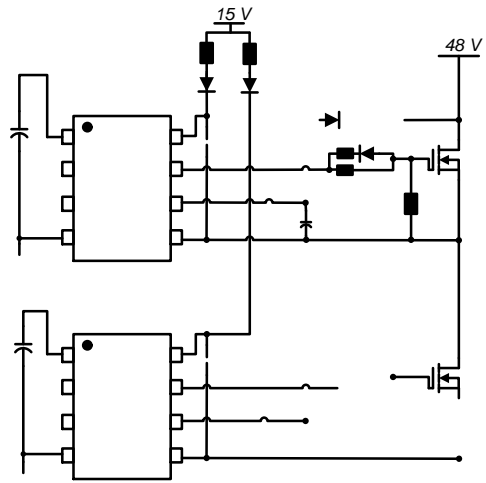
The Fault control logic in Figure 8 to allow active discharge is explained below:



**Figure 8. Example of Fault**

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HS1\_out



### **Bootstrap Drive Circuit Operation**

Both the FAD3151 and the FAD3171 normally use the bootstrap technique to achieve an elevated gate drive voltage in high side operation. This bootstrap power supply technique has the advantage of being simple and low cost.





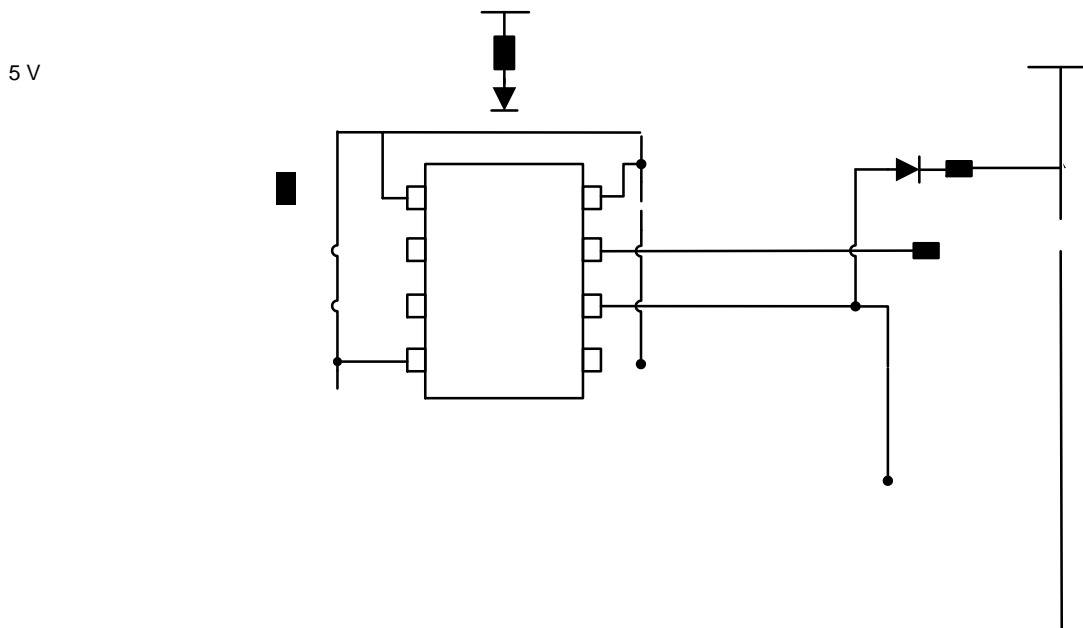
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- iii. When  $P_1$  turns off, the desat current flows into  $C_{ext}$  and charges it until the voltage at the desat terminal rises to the desat threshold,  $V_{desat+}$ . When  $V_{desat}$  exceeds the internal  $V_{desat+}$ , a fault status is triggered at the FLT pin of high side driver.
- iv. The fault status is cleared when the self-check signal for high side driver is turned off.
- A malfunction of the high side desat protection circuit is detected:
  - ◆ if the high side gate driver is unable to trigger (set) a fault status on the FLT pin during self-check, or
  - ◆ if the gate driver is unable to clear this fault status at the end of self-check.
- During self-check mode of low side gate driver, the output of the high side gate driver should be turned off. The self-check sequence for low side desat protection circuit is as follows: (Please refer to the low side components in Figure 13 and the self-check sequence in Figure 14 for details.)
  - i. The microcontroller provides a low side self-check signal to turn on transistor  $N_2$ . At the same time, the

output of the low side gate driver is turned on. As a result,  $P_1$  turns off.

- ii. When  $P_1$  turns off, both the  $I_{CE}$  of  $N_2$  and  $I_{desat}$  can charge  $C_{ext}$ . In comparison to  $I_{desat}$ , the  $I_{CE}$  of  $N_2$  could be significantly higher. Therefore,  $C_{ext}$  is rapidly charged. When  $V_{desat}$  is higher than  $V_{desat+}$ , a fault status is triggered at the FLT pin of low side driver.
- iii. The fault status is cleared when the self-check signal and the input signal for low side driver are turned off.
- A malfunction of the low side desat protection circuit is detected:
  - ◆ if the low side gate driver is unable to trigger (set) a fault status on the FLT pin during self-check, or
  - ◆ if the low side gate driver is unable to clear this fault status at the end of self-check.

NOTE: The desat self-check circuit shown for high side can also be adopted for low side. The low side desat self-check circuit shown in Figure 13 has fewer components than the self-check circuit on high side.



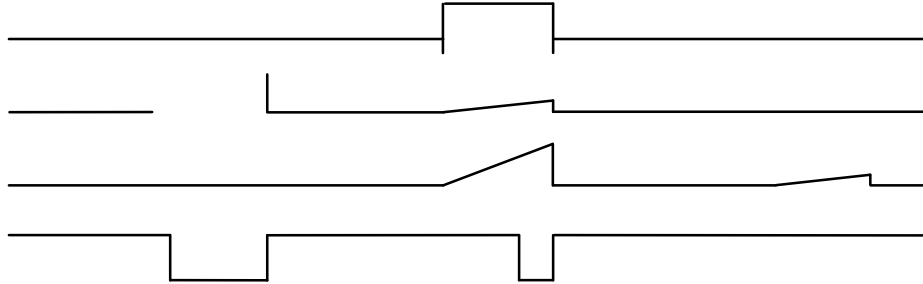


Figure 14. Self-check Sequence for High Side and Low Side Gate Driver

Table 2. FAILURE MODE ANALYSIS OF THE DESAT SELF-CHECK CIRCUIT FROM FIGURE 13

Component	Failure Mode	Effect and Diagnosis of Failure	Behavior
D <sub>3</sub>	Open	<ul style="list-style-type: none"> <li>Does not allow P<sub>1</sub> to turn off during self-check; this can be detected during self-check as a fault status is triggered on the FLT pin.</li> </ul>	Safe
	Short	No issues	Safe
P <sub>3</sub>	Open	Does not allow P <sub>1</sub> to turn off during self-check; this can be detected as a fault status is triggered on the FLT pin.	Safe
	Short	<ul style="list-style-type: none"> <li>Pulls up the gate of P<sub>1</sub> consistently.</li> <li>Causes an inadvertent triggering of the desat fault.</li> </ul>	Safe
R <sub>2</sub>	Open	<ul style="list-style-type: none"> <li>This can be detected during self-check.</li> <li>The FLT pin is able to trigger a fault status but is unable to clear it.</li> </ul>	Safe
	Short	<ul style="list-style-type: none"> <li>Pulls down the gate of P<sub>1</sub> to ground and does not allow P</li> </ul>	